



POMA-35

The POMA-35 represents a breakthrough in mobile satellite technology, establishing itself as the world's most compact and advanced Land-on-the-Move (OTM) antenna system. Engineered for exceptional reliability and performance on the move, it provides seamless, real-time connectivity for mission-critical operations across both Ku and Ka frequency bands.

Despite its minimal footprint, the POMA-35 delivers robust performance with the option for simultaneous Ku/Ka dual-band functionality without the need to change the feed. Its innovative design incorporates a highly reliable direct drive mechanism for precise azimuth (AZ) and elevation (EL) control, paired with a cap design feed for maximum efficiency and significantly reduced side lobes.

A key feature of the POMA-35 is its self-contained operation. It operates completely independent of GPS, utilizing advanced satellite beacon tracking to automatically correct gyro drift. The system requires only a one-time manual input of local latitude and longitude for initial setup, ensuring operational security and simplicity.

Key Features

- Available in Ku and Ka Bands
- High Tracking Accuracy, the Tracking error <0.5 dB RMS without blockage
- Good Tracking Stability, the AZ system uses a closed-loop stabilization algorithm for precise satellite tracking, even during fast movements or "S" travel
- Blockage recovery in <3 seconds for blockage times <5 minutes; recovery in <5 seconds for blockage times <20 minutes
- Dynamic Pointing and Switching enables real-time satellite pointing and seamless satellite switching while in motion.
- Supports OpenAmp
- Optional 4G / 5G / LTE supported modem for load balancing and bonding solutions



Environmental Data	
Operating wind speed	Max.60m/s at any direction
Working temperature	-40°C~+55°C
Storage temperature	-55°C~+70°C
Protection grade	IP65
Working humidity	0%~98%

RF performance data													
Aperture	0.35m												
Reflector material	Carbon fiber												
Antenna form	Circular symmetrical reflector and cap feed												
	Ku-Band 2 ports, Linear polarized Feed												
	Ka-Band 2 ports, circular polarized Feed												
Working frequency (GHz)	<table border="1"> <thead> <tr> <th>Rx</th><th>Tx</th><th>Rx</th><th>Tx</th></tr> </thead> <tbody> <tr> <td>10.70</td><td>13.75</td><td>18.7</td><td>29.0</td></tr> <tr> <td>12.75</td><td>14.50</td><td>20.2</td><td>30.0</td></tr> </tbody> </table>	Rx	Tx	Rx	Tx	10.70	13.75	18.7	29.0	12.75	14.50	20.2	30.0
Rx	Tx	Rx	Tx										
10.70	13.75	18.7	29.0										
12.75	14.50	20.2	30.0										
POL form	H/ V linear												
Antenna Gain (dBi)	30.6+20lg(f/12.25)												
	32.0+20lg(f/14.0)												
	35.0+20lg(f/19.6)												
	38.3+20lg(f/29.4)												
Antenna Pattern Compliancy	ITU-R S.580-6 and ITU-R S.465-6												
Cross POL (dB)	35 (axisl)												
Axial ratio (dB)	-												
Tx-Rx isolation (dB)	85												
	-												
Rx-Tx isolation (dB)	-												
	30												
	-												
EIRP (dBw)	47.2 (50W BUC)												
G/T (dB/k)	9.6												
	-												
	11												
	-												

Mechanical	
AZ Motion Range	360° continuous rotation without limit
EL Motion Range	-5°~ 100°
POL Motion Range	± 110°
AZ Revolution	100°/s
EL Revolution	100°/s
AZ Acceleration	200°/s ²
EL Revolution	200°/s ²
Pointing Accuracy	≤0.2° (R.M.S)
Initial Acquisition Time	≤2min
Blockage Recovery Time	≤5s (cover for 5 minutes)
Weight of Product	≤10Kg
Radome Size	Φ420×595 mm (D× H)

Electrical data	
Power supply of system	DC18~36V
Positioning mode	GPS
Steady type	3-axes for stability, 4-axes for tracking

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